



Acoustic biomass estimates of southern blue whiting on the Bounty Platform in 2013

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R.L.O'Driscoll
J. Oeffner
A.J. Dunford

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PO Box 2526
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EXECUTIVE SUMMARY

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The FV *Tomi Maru* 87 collected acoustic data along 45 transects in four snapshots on the Bounty Platform between 18 and 25 August 2013. All snapshots surveyed the main southern blue whiting (SBW) aggregation south of the Bounty Islands, which moved to the east during the survey period. The surveyed areas in the four snapshots ranged from 132 to 259 km², much larger than the survey areas in 2012, when eight completed snapshots only covered 10–41 km². The first snapshot in 2013 did not completely cover the main aggregation, with significant SBW marks occurring on the outermost (northwestern) transect. Coverage in the other three snapshots was better, with only very low densities of fish detected on the outer transects and at the end of transects. High densities of SBW were observed in all snapshots, with peak densities in snapshot 2 on 20 August. Spawning appeared to be late in 2013, with the few running ripe females caught before 23 August.

Biomass estimates for 2013, estimated using the new target-strength-to-fork-length relationship for SBW (based on recent *in situ* measurements and adopted in 2012), ranged from 14 364 t (CV 30%) in snapshot 4 to 44 517 t (CV 46%) in snapshot 2. The “best” estimate of 28 533 t (CV 27%) was based on the average of snapshots 2–4. Estimates from previous industry acoustic surveys in the Bounty time-series were re-calculated in 2013 to correct for an error in the analysis software and inconsistencies in the estimation of calibration parameters. These changes increased estimates from surveys in 2004–12 by 0–25%. The estimate of SBW biomass in 2013 was higher than the re-calculated biomass from 2009–12 (16 333–20 990 t), but less than half of the estimates from 2007 (79 285 t) and 2008 (75 899 t). In 2013, transects crossing the high density aggregation were an average of 4.7 n. miles long, compared to less than 3 n. miles in 2012, but 8 n. miles long in 2008.

Data on the size distribution of the fish, collected by Ministry for Primary Industries observers, show that this fishery is still dominated by fish from the strong 2002 year-class, but the proportion of younger fish (mainly from the 2007 year-class) has increased.

1. INTRODUCTION

Southern blue whiting (*Micromesistius australis*) is one of New Zealand's largest volume fisheries, with annual landings of between 25 000 t and 40 000 t since 2000 (Ministry for Primary Industries 2013). Southern blue whiting (SBW) occur in Sub-Antarctic waters, with known spawning grounds on the Bounty Platform, Pukaki Rise, Auckland Islands Shelf, and Campbell Island Rise (Hanchet 1999). Fish from the four spawning grounds are treated as separate stocks for stock assessment. Spawning occurs on the Bounty Platform from mid-August to early September and 3–4 weeks later in the other areas.

A programme to estimate SBW spawning stock biomass on each fishing ground using acoustic techniques from research vessels began in 1993. The Bounty Platform, Pukaki Rise, and Campbell Island Rise were each surveyed annually between 1993 and 1995. After the first three annual surveys it was decided to survey these areas less regularly. The Bounty Platform grounds were surveyed in 1997, 1999, and most recently in 2001. The Pukaki area was surveyed in 1997 and 2000. The only on-going series of research surveys is on the Campbell Island Rise grounds, which have been surveyed in 1998, 2000, 2002, 2004, 2006, 2009, 2011, and 2013. All these surveys were carried out from *R.V. Tangaroa* using towed transducers and have been wide-area surveys intended to survey spawning SBW and pre-recruits. The results of these research surveys of spawning and pre-recruit SBW are the main input into SBW stock assessments (e.g., Ministry for Primary Industries 2013).

An acoustic survey of the Campbell Island grounds was carried out from FV *Aoraki* in 2003 and showed that industry vessels with hull-mounted acoustic systems could also be used to collect acoustic data on SBW in good weather (less than 25 knots of wind) (O'Driscoll & Hanchet 2004). They further demonstrated that snapshots of the main spawning aggregations could be carried out using the processing time between commercial trawls without seriously compromising fishing success. Further surveys of spawning SBW using this approach have been carried out on the Bounty Platform in 2004, 2006, 2007, 2008, 2009, 2010, 2011, and 2012, on the Pukaki Rise in 2009 and 2010, and on the Campbell Island Rise in 2010. Surveys from 2004–09 were summarised by O'Driscoll (2011a), with results from surveys in 2010–13 presented by O'Driscoll (2011b, 2011c, 2012, 2013).

Very strong SBW marks were observed during the industry survey of the Bounty Platform in 2007 and 2008 (O'Driscoll 2011a). The 2007 survey results suggested that the spawning stock size on the Bounty Platform had increased substantially since the 2005 assessment (Hanchet 2005), and, when taken in conjunction with data on the size and age distribution of the fish caught in the fishery, was indicative of very good recruitment from the 2002 year-class. As a result of this survey, the TACC for Bounty Platform SBW was increased to 10 000 t in 2008. The 2008 acoustic survey confirmed the large increase in SBW spawning stock size and the TACC was further increased to 15 000 t from 1 April 2009. However, estimated acoustic biomass on the Bounty Platform declined by a factor of four in 2009 (O'Driscoll 2011a), and this decline was supported by results from the 2010–12 surveys (O'Driscoll 2011b, 2012, 2013). The observed decline between 2008 and 2009 was too great to be explained solely by fishing and average levels of natural mortality of the 2002 year class (Ministry for Primary Industries 2013). Due to the low biomass estimates in 2009 and 2010, and the uncertainty in how to interpret the changes in acoustic indices, the TACC for SBW6B was decreased to 6860 t from 1 April 2011 (Ministry for Primary Industries 2013). In 2013, the fishing industry agreed to voluntarily 'shelve' 2860 t of quota, so the catch limit for the Bounty Platform in 2013 was 4000 t.

Given the recent changes in TACC and ongoing uncertainty about the status of the Bounty Platform stock, it is very important to continue to monitor acoustic estimates of spawning SBW in that area. The 10-year research programme for deepwater fisheries identifies the need for annual acoustic surveys from industry vessels on the Bounty Platform. A further aggregation-based survey was therefore carried out from FV *Tomi Maru 87* in August 2013 following the same protocols as in 2004–12 (O'Driscoll 2011a).

1.1 Project objectives

This report is the final reporting requirement for Ministry for Primary Industries Research Project SBW2010/02C. The objective of this project is to continue the time-series of acoustic estimates of abundance of spawning SBW on the Bounty Platform using aggregation-based acoustic estimates from industry vessels.

2. METHODS

2.1 Vessel and equipment

FV *Tomi Maru 87* is a 68 m Japanese surimi trawler chartered by Aurora Fisheries Ltd. The vessel is fitted with a Simrad ES70 echosounder. The Simrad ES70 was installed on *Tomi Maru 87* in April 2010 and is an updated version of the previous ES60 echosounder. Most of the developments to the echosounder are software-based, and the unit uses the same general purpose transceiver (GPT) and hull-mounted 38-kHz split-beam transducer as the ES60.

Calibration of the Simrad ES70 echosounder on *Tomi Maru* took place off Timaru on 1 July 2013 (Appendix 1). Diagnostics indicated a calibration of excellent quality. The estimated peak gain (G_0) in 2013 based on the mean sphere echo was very similar to that estimated from 2012 (Appendix 1). The 2013 calibration values from Table A3 in Appendix 1 were used in this analysis. ES70 transceiver settings and other relevant parameters during data collection are given in Table 1.

2.2 Survey design

The aim was to cover the main SBW aggregation(s) using an adaptive design. Detailed written instructions on survey design (described in O'Driscoll 2011a) were translated into Japanese, and vessel officers on FV *Tomi Maru 87* were also personally briefed by a NIWA staff member (Adam Dunford) in Timaru on 8 August 2013.

Vessel officers were instructed to collect acoustic data continuously while trawling and searching to allow examination of the spatial distribution of fish. However, estimating SBW abundance requires a number of straight, parallel lines (transects) across an aggregation. Each of these transects was to be run at a constant speed (usually 6–10 knots), with a separate, documented, acoustic file. Transect spacing and orientation was dependent on the size and shape of the aggregation and the prevailing weather conditions, but the aim was to obtain 5–10 transects at regular intervals (e.g., 1 n. mile) across each aggregation. The importance of ensuring that transects were long enough and numerous enough to fully encompass the main aggregation(s) was emphasised. Previous acoustic surveys of the Bounty Platform have shown that SBW are very hard to survey acoustically during the day (Hanchet et al. 2000), therefore it was requested that all transects be carried out at night.

Clear instructions were also provided on protocols for acoustic data collection, including use of standard scientific settings on the echosounder, turning other acoustic equipment off to avoid interference, and collecting data in suitable weather conditions.

2.3 Acoustic data analysis

Acoustic data were provided to NIWA as .raw ES60 files. Data from acoustic transects were extracted and analysed using NIWA's custom ESP2 software (McNeill 2001). Echograms were visually examined, and the bottom determined by a combination of an in-built bottom tracking algorithm and manual editing. Noise spikes and missing pings were manually defined as 'bad transmits' so these were not included in subsequent analysis. Regions corresponding to spawning SBW were then identified. Marks were

classified subjectively based on their appearance on the echogram (shape, structure, depth, strength, etc.) after Hanchet et al. (2002b).

Backscatter from marks (regions) identified as SBW was then integrated to produce an estimate of acoustic density (m^{-2}). During integration, acoustic backscatter was corrected for a systematic error in ES60 and ES70 data (Ryan & Kloser 2004) and calculated sound absorption by seawater. In July 2013, an error was found in the software that applied the triangle wave correction for short files (less than 1360 pings), where the correction could not be established from the data. This bug led to a small negative bias in estimates of backscatter (i.e., biomass was underestimated) and affected all previous Bounty surveys from industry vessels. The bug was fixed before analysis of the 2013 data, but required all previous surveys to be re-converted and integrated (see Section 2.5).

The estimated sound absorption was 9.47 dB km^{-1} , which was the same value used for previous Bounty surveys (O'Driscoll 2011a), and was based originally on data collected on the Campbell Island Rise in 2006 (O'Driscoll et al. 2007). No correction was applied for vessel motion. A Microstrain 3DM-GX1 gyro-enhanced orientation sensor was used to record vessel motion on FV *Tomi Maru 87* in 2006, but O'Driscoll et al. (2006) found that correcting for the effects of vessel motion (Dunford 2005) had very little effect (less than 1%) on biomass estimates in good weather and sea conditions because of the relatively shallow depth. Motion sensors were not fitted to FV *Tomi Maru 87* in 2013.

Acoustic density was output in two ways. First, average acoustic density over each transect was calculated. These values were used in biomass estimation. Second, acoustic backscatter was integrated over 10-ping bins (vertical slices) to produce a series of acoustic densities for each transect (typically 20–100 values per transect). These data had a high spatial resolution, with each value (10 pings) corresponding to about 100 m along a transect, and were used to produce plots showing the spatial distribution of acoustic density.

2.4 Biomass estimation

Acoustic density estimates were converted to SBW biomass using a ratio, r , of mean weight to mean backscattering cross section (linear equivalent of target strength) for SBW. This ratio for the Bounty Platform was calculated from the scaled length frequency distribution of SBW caught by FV *Tomi Maru 87* in this area in 2013, estimated from scientific observer data (Figure 1).

Acoustic target strength was derived using the new target-strength-to-fork-length (TS-FL) relationship for SBW of O'Driscoll et al. (2013):

$$TS = 22.06 \log_{10} FL - 68.54 \quad (1)$$

where TS is in decibels and FL is in centimetres. This TS-FL relationship was based on *in situ* measurements made using a net-mounted acoustic-optical system (AOS) on the Campbell Island Rise in 2011 (O'Driscoll et al. 2013), and was adopted by the Middle Depth Fishery Assessment Working Group (MIDWG) in 2012. Previous estimates in the Bounty SBW time-series were updated to take account of the change in TS-FL relationship by O'Driscoll (2013).

Mean SBW weight, w (in grams), was determined using the combined length-weight relationship for spawning SBW from Hanchet (1991):

$$w = 0.00439 \times FL^{3.133} \quad (2)$$

The mean length of SBW caught at the Bounty Platform in 2013 by FV *Tomi Maru 87* was 40.4 cm. Mean weight and mean backscattering cross-sections were obtained by transforming the scaled length frequency distribution in Figure 1 by equations (1) and (2) and then calculating the means of the

transformed distributions. Mean weight was 484 g. Mean backscattering cross-section was 0.000494 m² (equivalent to -33.1 dB), giving a ratio, r , of 981 kg m⁻².

Biomass estimates and variances were obtained from transect density estimates using the formulae of Jolly & Hampton (1990). The surveyed areas (Table 2) were calculated from transect start and finish positions using the formula: $a = nLW$ where n is the number of transects, L is the mean length of transects, and W is the mean transect spacing. Biomass estimates and CVs were then estimated with and without removing “zero-transects” (i.e., the leading and trailing transects, which define the extent of the aggregation). Cordue (2008) suggested that inclusion of zero transects may overestimate CVs using the Jolly & Hampton (1990) methodology. Only whole transects with zero density were removed. No attempt was made to remove parts of transects with zero density, as most non-zero transects had SBW over most of their length.

2.5 Update of Bounty acoustic time-series

As noted in Section 2.3, an error was found in the software that applied the triangle wave correction for short files in July 2013. This bug led to a small negative bias in estimates of backscatter (i.e., biomass was underestimated) and affected all previous Bounty surveys from industry vessels. Acoustic data from all previous surveys were therefore re-converted and integrated in October 2013 using updated (corrected) software. This led to increases in abundance estimates by 0–8% (average 3%).

At the same time, we also re-examined the calibration coefficients used for estimating abundance, and noted that there was inconsistency in the method used to estimate the peak transducer gain (G_0). Estimates from 2004–08 used G_0 based on fitted sphere TS, while those from 2009–12 used G_0 based on maximum sphere TS. This was due to a change in calibration software in 2008. Calibration values estimated using fitted or mean sphere TS are more consistent and stable than values based on maximum sphere TS (see Figure A3), and we decided to re-calculate all previous estimates in the Bounty time-series using G_0 values based on mean sphere TS. This change ensures consistency with acoustic methodology for industry surveys of other deepwater species (hoki, orange roughy), and those using towed acoustic equipment (e.g., Campbell SBW survey), which already use calibration values based on mean sphere TS. The change in estimated calibration coefficients increased estimates from Bounty surveys in 2009–12 (previously based on maximum sphere TS) by 9–19%, but values from 2004–08 (previously based on fitted sphere TS) changed by less than 1%.

3. RESULTS

3.1 Acoustic data collection

Acoustic data were recorded continuously from *FV Tomi Maru 87* from departing Timaru on 10 August 2013 to arriving back in port on 29 August 2013. The vessel was on the Bounty Platform fishing grounds from 12 to 26 August. Although data collected while fishing and searching was affected by acoustic noise due to sonar and other instruments and is not suitable for quantitative analysis, these data do provide a useful record of vessel activities and the presence of fish outside surveyed areas (e.g., O’Driscoll 2011b).

Forty five acoustic transects were carried out in four snapshots on the Bounty Platform between 18 and 25 August 2013 (Table 2). As requested, all transects were carried out at night. All snapshots surveyed the main SBW aggregation south of the Bounty Islands, which moved to the east during the survey period (Figure 2). This movement pattern is consistent with the migration pattern of spawning SBW on the Bounty Platform in previous years (e.g., Hanchet & Grimes 2000, Hanchet et al. 2002a, Figure 2). Transects in all four snapshots were run from east to west (i.e., counter to the expected direction of fish movement) to reduce the risk of bias due to double counting.

Surveyed areas in 2013 ranged from 132 to 259 km² (Table 2), much larger than the survey areas in 2012, when eight completed snapshots only covered 10–41 km² (O’Driscoll 2013), but within the range surveyed in previous years when snapshot areas were 50–300 km² (O’Driscoll 2011a, 2012). The spacing between adjacent transects was about 2 km, again greater than in 2012, when average transect spacing was 700–1000 m, but within the typical range of spacing (2–3 km) in previous surveys. Fewer snapshots were carried out in 2013 than in 2011 and 2012 (eight completed snapshots in each year). This was due to unsuitable (rough) weather conditions for much of the voyage, and also advice from NIWA that it was “better to do fewer snapshots with good coverage than many poor ones”.

The survey duration covered by the four snapshots (8 days) was less than in 2011 (when survey duration was 13 days), but similar to that in 2012 (9 days), and greater than in most previous surveys (Figure 3). Between 2004 and 2010 there was a trend in survey dates occurring earlier over the Bounty Platform time series (Figure 3). Timing of SBW spawning has also varied between years (Figure 3). Spawning appeared to be late in 2013, with the few running ripe females recorded by scientific observers before 23 August. The 2013 survey was therefore before and during the main spawning period.

3.2 Acoustic data quality

The quality of the acoustic data from Bounty Platform in 2013 was good during three of the four snapshots, but there were ping drop-outs due to bubble aeration in snapshot 3 (e.g., Figure 4). ES70 transceiver settings and other relevant parameters during data collection (see Table 1) followed recommended protocols.

3.3 Acoustic mark types

Relatively dense adult SBW marks were observed in all snapshots. Marks were usually within 100 m of the bottom in 250–400 m water depth (e.g., Figures 4–6). Aggregations got shallower during the survey period. Mark identification of adult SBW is relatively certain at the Bounty Platform (Hanchet et al. 2002b).

3.4 Distribution of SBW backscatter

The spatial distribution of SBW along each transect in the four snapshots is shown in Figure 7. As noted in Section 3.1, transects in all snapshots were carried out sequentially from east to west.

The first snapshot did not completely cover the main aggregation, with significant SBW marks occurring on the outermost transect at the northwest of the surveyed area (transect 12) (Figures 6–7). Coverage in the other three snapshots was better, with only very low densities of fish detected on the outer transects and at the end of transects. High densities of SBW were observed in all snapshots, with peak densities in snapshot 2 on 20 August (see Figure 5). Fish densities were comparable with those seen in previous surveys, including the high biomass years of 2007 and 2008 (Figure 8). In 2013, transects crossing the high density aggregation were an average of 4.7 n. miles long, compared to less than 3 n. miles in 2012, but 8 n. miles long in 2008 (e.g., Figure 8).

3.5 Biomass estimates

Biomass estimates for all Bounty Platform snapshots in 2004–13 are given in Table 3. As described in Section 2.5, estimates from 2004–12 were recalculated to correct for a bug in the conversion script and inconsistencies in the estimation of calibration coefficients. These changes increased abundance estimates from those previously published by O’Driscoll (2013) by 0–25% (Table 4).

The variance of snapshot estimates is reduced by removing zero transects (see Table 3), but the differences are small, as there are relatively few zero transects (only six in 2013). Note that the biomass estimate sometimes changed with the exclusion of zero transects as the transect spacing was not always uniform.

Acoustic biomass estimates for the four snapshots in 2013, with zero transects removed, ranged between 13 592 t (CV 30%) for snapshot 4 and 44 517 t (CV 46%) for snapshot 2 (see Table 3). At its meeting on 9 December 2013, the MIDWG agreed that the “best” estimate of the SBW spawning aggregation in 2013 was the average estimate from snapshots 2–4. Snapshot 1 was not included in the average as it did not completely cover the main aggregation (see Section 3.4). The average of snapshots 2–4 was 28 533 t (Table 4). The sampling precision of the average estimate was calculated in two ways. The first method was to average the variances from each snapshot, which gave a CV of 27%. The second method assumes that the snapshot abundance estimates are independent and identically distributed random variables. The sample variance of the snapshot means divided by the number of snapshots is therefore an unbiased estimator of the variance of the mean of the snapshots. The CV estimated by this second method was 31%.

The ‘best estimate’ from 2013 was higher than the re-calculated biomass from 2009–12 (16 333–20 990 t), but less than half of the estimates from 2007 (79 285 t) and 2008 (75 899 t) (Table 5). However, the MIDWG agreed that industry acoustic surveys do not provide a consistent time-series of SBW abundance on the Bounty Platform.

4. DISCUSSION

Data on the size distribution of the fish (see Figure 1) show that the fishery in 2013 is still dominated by fish from the strong 2002 year-class (modal length 43 cm for females and 40 cm for males), but that the proportion of younger fish is increasing. This is apparent as a smaller mode at length 39 cm for females and as a shoulder on the main mode for males. Ageing suggests that these younger fish are mainly from the 2007 year-class, observed at age 6 in 2013.

The very large decrease observed in acoustic estimates of SBW at the Bounty Platform between 2008 and 2009 was too great to be explained by fishing and average natural mortality on the dominant 2002 year-class. O’Driscoll (2011a) considered three other potential explanations for the large apparent decline in biomass:

1. Changes in acoustic survey methodology and equipment.
2. Changes in timing and extent of survey coverage.
3. Movement of fish from the Bounty Platform to other areas.

Acoustic methodology, analysis, and equipment were consistent between years and based on comparisons of the length frequency distribution of the fish, there was no evidence of movement of fish from the Bounty Platform to other areas. Therefore O’Driscoll (2011a) concluded that the very large changes in estimated SBW abundance were probably related mainly to the timing and extent of survey coverage, and that the 2009 survey probably did not encompass the entire spawning aggregation. This conclusion was re-evaluated in light of the more extensive surveys in 2010–12, which supported the low biomass observed in 2009 (O’Driscoll 2011b, 2012, 2013). It is still only possible to speculate on the causes of this decline, but suggested causes include an unusually high natural mortality (Ministry for Primary Industries 2013).

The estimated biomass increased by 75% in 2013 (see Table 5). It is uncertain whether this increase was a function of improved survey coverage, an increase in the spawning population – perhaps due to recruitment of younger year-classes, or both.

An updated assessment of the Bounty Platform SBW stock was carried out in 2013 using data up to, and including, 2012 (Ministry for Primary Industries 2013). The series of industry vessel surveys was assumed to be a time series with non-constant catchability, with survey catchability coefficients (q)

related to the wide-area acoustic survey estimates via a q ratio prior. The MIDWG considered two model runs: the first assumed a prior that constrained the catchability coefficients of the 2007 and 2008 surveys to be similar to the catchability coefficient of the wide-area *Tangaroa* Bounty surveys, but relaxed the constraint on surveys since 2009 (i.e., effectively down-weighting the surveys from 2009–12, labelled run 2.3); and the second, where the catchability coefficients of the 2009–12 surveys were constrained to be similar to the catchability coefficient of the wide-area surveys, but were relaxed for the 2007 and 2008 surveys (i.e., effectively down-weighting the surveys from 2007–08, labelled run 2.2). Neither of these runs provide a satisfactory fit to the industry acoustic time-series but the MIDWG considered that they provided useful information to assist managers, based on optimistic and pessimistic scenarios (Ministry for Primary Industries 2013). Both model runs estimated that SBW biomass in 2012 was between 35 and 45% B_0 and unlikely to be below the soft limit of 20% B_0 for the stock. However, biomass was projected to decline over the next 5 years at the current catch level as the 2002 year class is fished down (Ministry for Primary Industries 2013). As a consequence of this assessment, the fishing industry agreed to voluntarily ‘shelve’ 2860 t of SBW6B quota, so the catch limit for the Bounty Platform in 2013 was 4000 t.

In the most recent stock assessment of the Bounty Platform, in 2014, the model was unable to reconcile the high biomass estimate from the 2013 survey with the series of low biomass estimates between 2009 and 2012 (Ministry for Primary Industries 2014). Although a new moderately strong 2007 year class has entered the fishery, it was not large enough to account for the large increase in biomass seen during the survey. The only way that the model could reconcile these survey estimates was by estimating a much higher catchability for the 2013 survey. Indeed, in that context, the results of the 2013 survey were more consistent with the results of the 2007 and 2008 surveys.

The inconsistency in the ability of the aggregation type survey to reliably monitor the same proportion of the population each year has led to a non-robust stock assessment of the Bounty stock with high uncertainty (Dunn & Hanchet 2011, Ministry for Primary Industries 2013, 2014). Without a wide-area survey periodically to provide a ‘ground truthing’ for such aggregation survey results, this will be an on-going problem. While the data collected from aggregation surveys are useful for determining if evidence exists for a change in status, they cannot be used to determine the extent of that change. Put simply, it is impossible to determine whether changes in observed biomass are due to variability in the survey coverage or to real changes in stock size.

5. CONCLUSIONS

Acoustic data from the Bounty Platform in 2013 were collected with appropriate acoustic settings and were of sufficient quality to estimate biomass. The four snapshots were all in the region to the south of the Bounty Islands where the largest aggregations was observed in 2007–12 (see Figure 2) and were in the vicinity of the main commercial fishing effort on the survey dates. Survey design protocols were generally followed, and survey coverage was more extensive than in 2012, with three of the four snapshots appearing to adequately cover the aggregation.

The best biomass estimate for 2013, based on the average of snapshots 2–4 was 28 533 t (CV 27%). This was higher than the equivalent biomass from 2009–12 (16 333–20 990 t), but less than half of the estimates from 2007 (79 285 t) and 2008 (75 899 t).

Because of uncertainty about the proportion of fish surveyed every year, it is difficult to interpret results from aggregation-based acoustic surveys. It is uncertain whether the 75% increase in the acoustic index from 2012 to 2013 was a function of improved survey coverage, an increase in the spawning population – perhaps due to recruitment of younger year-classes, or both.

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8. TABLES

Table 1: Echosounder settings and other relevant parameters during acoustic data collection in 2013.

Parameter	Value
Echosounder	ES70
GPT model/serial	GPT Q38(4)-F1.0 009072056ac
GPT software version	070413
Echosounder software version	ES70 1.1.0
Transducer model	ES38B
Transducer serial number	1599
Operating frequency (kHz)	38
Transducer draft setting (m)	0.0
Transmit power (W)	2000
Pulse length (ms)	1.024
Transducer peak gain (dB)	26.5
Sa correction (dB)	0.0
Bandwidth (Hz)	2425
Sample interval (s)	0.192
Two-way beam angle (dB)	-20.60
Absorption coefficient (dB/km)	9.75
Speed of sound (m/s)	1500.0
Angle sensitivity (dB) alongship/athwartship	21.90/21.90
3 dB beamwidth (°) alongship/athwartship	7.10/7.10
Angle offset (°) alongship/athwartship	0.00/0.00

Table 2: Summary of acoustic snapshots carried out at the Bounty Platform in 2013 by *FV Tomi Maru 87*. Times are NZST.

Snapshot	Area (km ²)	Start time	End time	No. of transects
1	259.2	18 Aug 19:04	19 Aug 03:42	12
2	175.6	20 Aug 19:29	21 Aug 02:11	14
3	204.5	21 Aug 20:00	22 Aug 03:28	10
4	131.7	25 Aug 19:06	25 Aug 23:35	9

Table 3: Stratum areas, abundance estimates, and coefficients of variation (CV) for all snapshots of spawning SBW on the Bounty Platform carried out by industry vessels from 2004–13. All snapshots were carried out by *Tomi Maru 87* except M1 and M2 by *Meridian* and AB1 and AB2 by *A. Buryachenko* in 2009. Snapshots in bold were averaged to produce the biomass estimates in Table 4. All estimates calculated using the TS-FL relationship of O’Driscoll et al. (2013) and re-calculated in 2013 to correct for a bug in the conversion script and inconsistencies in the estimation of calibration parameters (see Section 2.5 for details).

Year	Snapshot	No. of transects	Calculated areas			No. of zero transects	Zero transects removed		
			Area (km ²)	Biomass (t)	CV (%)		Area (km ²)	Biomass (t)	CV (%)
2004	1	5	69.7	8 572	69	0	69.7	8 572	69
2006	1	7	199.4	12 600	16	0	199.4	12 600	16
	2	5	286.2	11 298	19	0	286.2	11 298	19
	3	4	41.3	1 327	34	0	41.3	1 327	34
	4	4	57.9	4 504	45	0	57.9	4 504	45
2007	1	7	234.5	4 100	38	1	199.0	4 081	35
	2	5	122.6	2 968	35	0	122.6	2 968	35
	3	5	250.2	85 700	35	1	218.5	89 629	29
	4&5	10	435.0	77 339	20	1	417.1	68 942	20
2008	1	6	260.4	119 017	45	1	230.8	117 675	43
	2	5	229.5	34 123	22	0	229.5	34 123	22
2009	M1	11	335.7	6 233	15	0	335.7	6 233	15
	M2	8	125.6	20 519	29	1	107.4	19 622	27
	1	3	232.3	14 067	42	0	232.3	14 067	42
	2	5	276.2	15 344	45	1	249.9	16 230	44
	AB1	7	38.8	3 858	26	0	38.8	3 858	26
	AB2	5	25.1	3 839	29	1	21.9	3 839	23
2010	1	6	52.5	2 770	51	0	52.5	2 770	51
	2	4	38.5	11 504	69	1	29.4	11 951	64
	3	9	85.7	17 426	37	2	77.0	18 074	35
2011	1	9	118.5	24 948	23	0	118.5	24 948	23
	2	11	136.7	6 762	17	0	136.7	6 762	17
	3	9	83.6	12 724	28	0	83.6	12 724	28
	4	7	53.9	6 614	34	2	43.9	6 614	30
	5	8	80.4	6 208	28	0	80.4	6 208	28
	6	8	76.8	14 090	44	2	60.7	14 090	42
	7	8	104.9	27 889	36	2	91.4	27 889	35
	8	9	132.2	6 304	21	0	132.2	6 304	21

Table 3 cntd: Stratum areas, abundance estimates, and coefficients of variation (CV) for all snapshots of spawning SBW on the Bounty Platform carried out by industry vessels from 2004–13. Snapshots in bold were averaged to produce the biomass estimates in Table 4. All estimates calculated using the TS-FL relationship of O’Driscoll et al. (2013) and re-calculated in 2013 to correct for a bug in the conversion script and inconsistencies in the estimation of calibration parameters (see Section 2.5 for details).

Year	Snapshot	No. of transects	Calculated areas			No. of zero transects	Zero transects removed		
			Area (km ²)	Biomass (t)	CV (%)		Area (km ²)	Biomass (t)	CV (%)
2012	1	6	23.9	3 524	49	1	20.3	3 591	45
	2	6	10.2	322	84	1	8.7	336	82
	3	6	17.8	1 771	45	0	17.8	1 771	45
	4	6	16.8	6 213	39	0	16.8	6 213	39
	5*	3	4.6	46	27	0	4.6	46	27
	6	10	32.9	16 386	16	1	30.4	16 288	14
		8	20.2	15 093	17	0	20.2	15 093	17
	8*	3	16.7	2 029	57	0	16.7	2 029	57
		8	28.2	17 618	18	0	28.2	17 618	18
	10	5	41.2	3 383	14	0	41.2	3 383	14
2013	1	12	259.2	21 051	31	1	251.1	21 051	31
	2	14	175.6	44 517	46	0	175.6	44 517	46
9	3	10	204.5	27 972	37	2	170.9	27 491	34
		9	131.7	14 364	36	3	94.0	13 592	30

* Snapshots 5 and 8 in 2012 were aborted due to fish movement or interference from other vessels

Table 4: Estimates of SBW spawning stock biomass (t) from acoustic estimates from industry vessels using old TS-FL relationship of Dunford & Macaulay (2006) (from O'Driscoll 2013), and estimates derived using new TS-FL relationship of O'Driscoll et al. (2013). All estimates in the time-series were also re-calculated in 2013 (see Table 3) to correct for a bug in the conversion script and inconsistencies in the estimation of calibration parameters (see Section 2.5 for details). Ratio is the ratio of the two estimates using O'Driscoll et al. TS. Values in bold show time-series recommended for use in assessment.

Year	Old conversion & calibration		Reconverted	CV (%)	Ratio
	Dunford & Macaulay (2006)	O'Driscoll et al. (2013)	O'Driscoll et al. (2013)		
2004	13 473	7 955	8 572	69	1.08
2006	21 765	12 043	11 949	12	0.99
2007	159 589	76 220	79 285	19	1.04
2008	144 187	72 707	75 899	34	1.04
2009	28 242	14 683	16 640	21	1.13
2010	27 782	14 437	18 074	35	1.25
2011	35 597	18 713	20 990	27	1.12
2012	26 150	13 660	16 333	7	1.20
2013	—	—	28 533	27	—

Table 5: Estimates of SBW biomass (t) for adult fish from research acoustic surveys of the Bounty Platform in 1993–2001 (from Fu et al. 2013), and ‘best estimates’ of spawning stock biomass (SSB) from acoustic estimates from industry vessels (with zero transects removed). Estimates in 2006–09 and 2011–13 were obtained by averaging selected snapshots. All estimates were calculated using the TS-FL relationship of O'Driscoll et al. (2013).

Year	<i>Tangaroa</i> Adult fish	Industry Vessel SSB
1993	43 338 (58%)	—
1994	17 991 (25%)	—
1995	17 945 (23%)	—
1997	27 594 (37%)	—
1999	21 956 (75%)	—
2001	11 784 (35%)	—
2004	—	8 572 (69%)
2006	—	11 949 (12%)
2007	—	79 285 (19%)
2008	—	75 899 (34%)
2009	—	16 640 (21%)
2010	—	18 074 (35%)
2011	—	20 990 (27%)
2012	—	16 333 (7%)
2013	—	28 533 (27%)

9. FIGURES

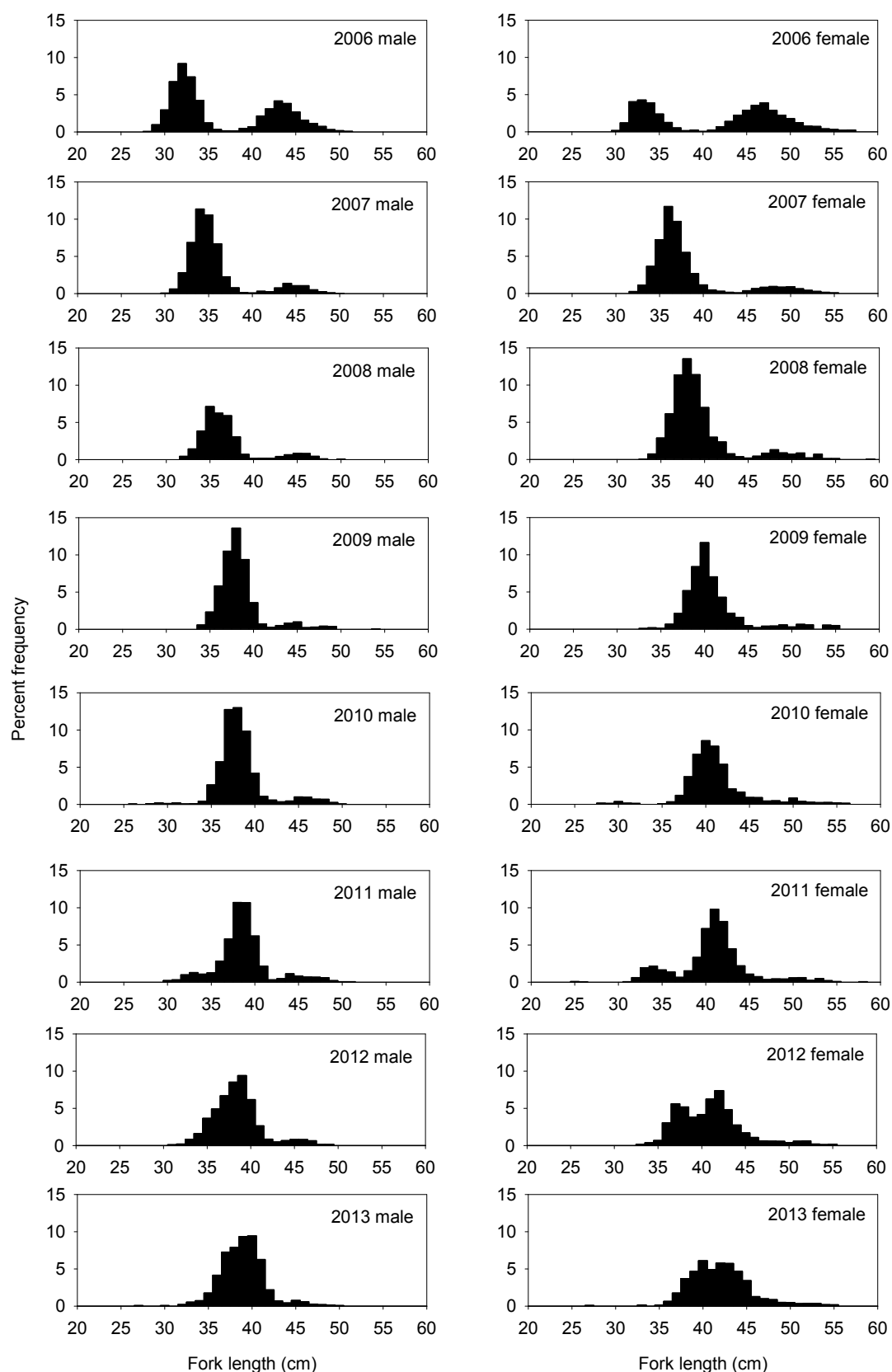


Figure 1: Scaled length frequency of SBW caught on the Bounty Platform by FV Tomi Maru 87 in 2006–13 based on scientific observer data. Data from 2013 are from observer trip 3837.

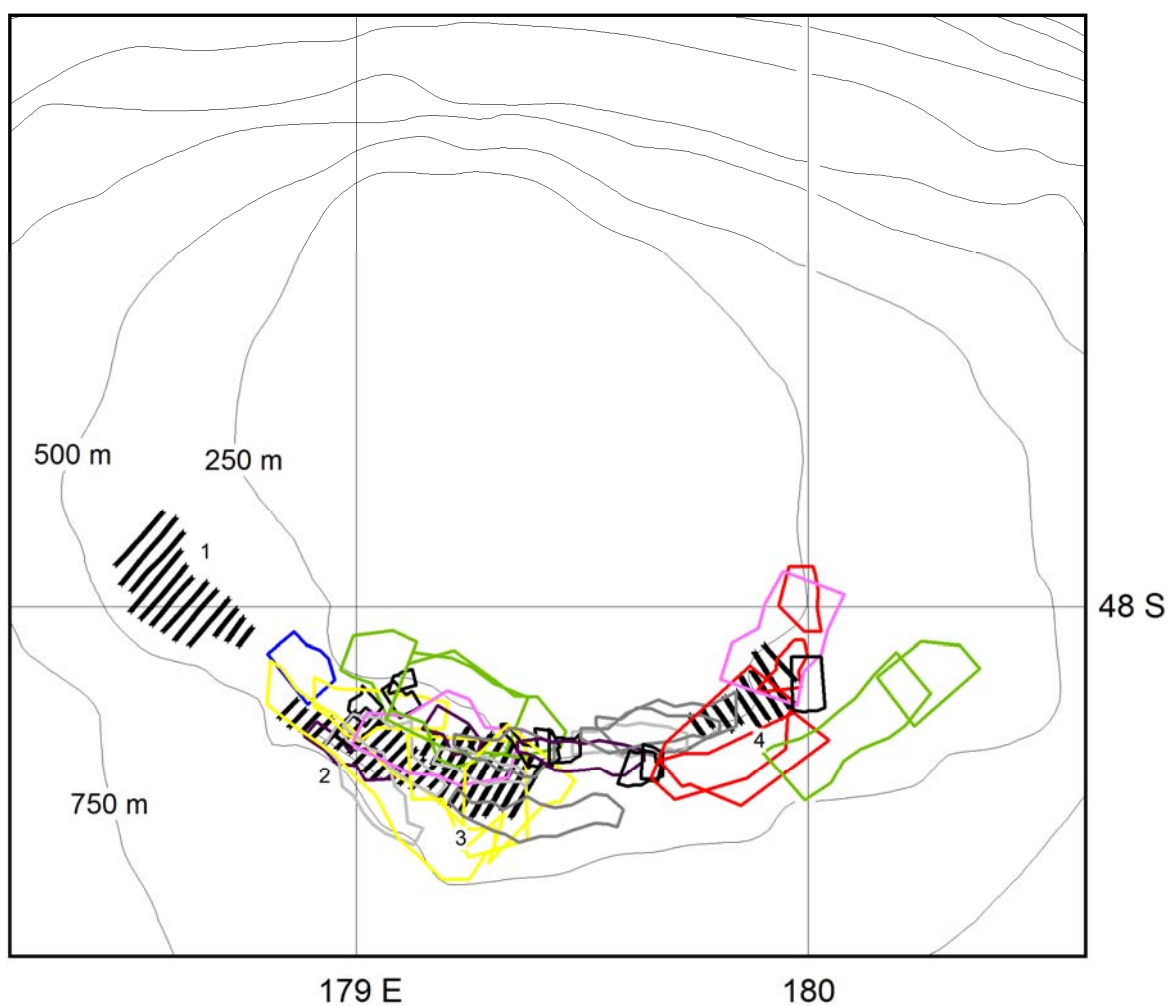


Figure 2: Map showing location of transects carried out in snapshots by *FV Tomi Maru 87* at the Bounty Platform in 2004–13. Transects for the four snapshots in 2013 (black lines) are compared with the areas surveyed in 2004 (blue), 2006 (red), 2007 (green), 2008 (pink), 2009 (yellow), 2010 (magenta), 2011 (grey), and 2012 (black).

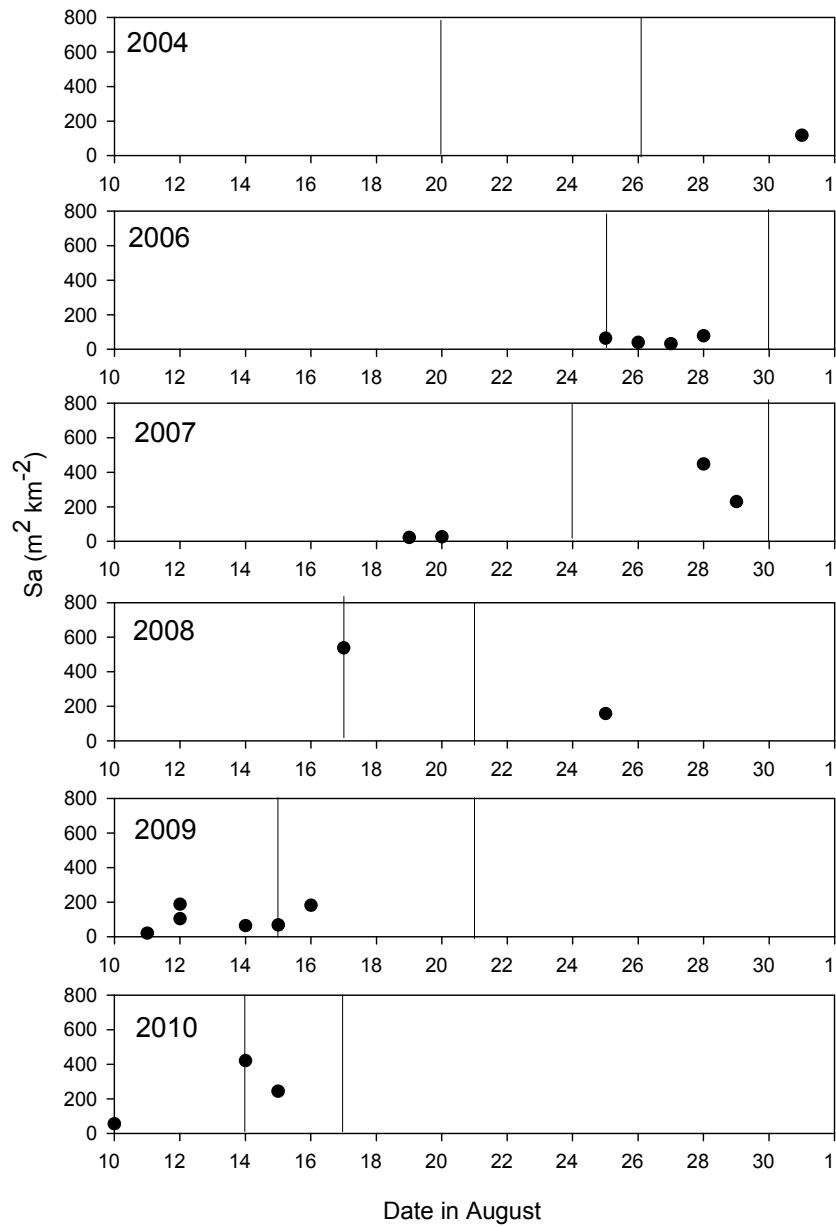


Figure 3: Weighted (by transect length) mean densities for each snapshot (solid circles) plotted as a function of date for all snapshots carried out by industry vessels on the Bounty Platform 2004–10. Vertical lines delineate estimated period of peak spawning based on gonad staging by observers.

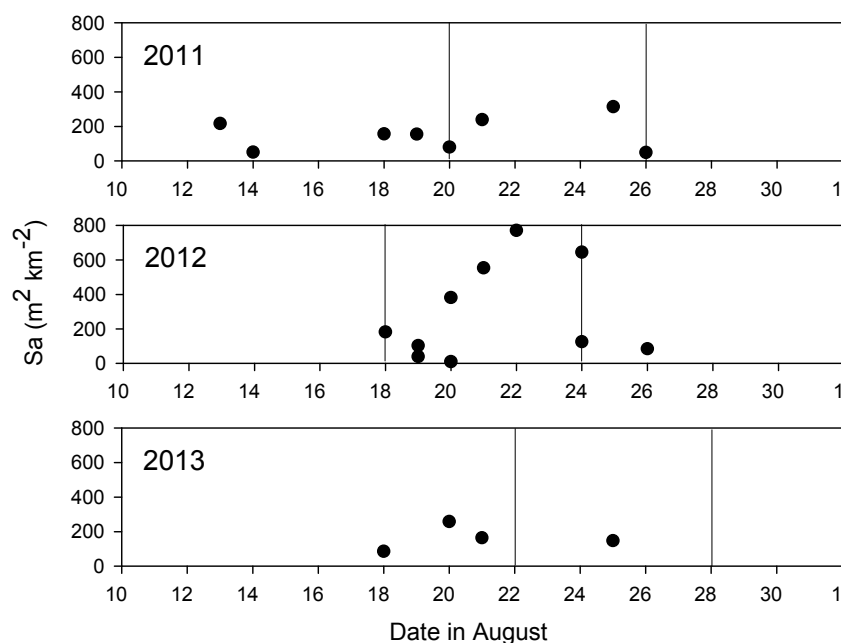


Figure 3 cntd: Weighted (by transect length) mean densities for each snapshot (solid circles) plotted as a function of date for all snapshots carried out by industry vessels on the Bounty Platform 2011–13. Vertical lines indicate estimated period of peak spawning based on gonad staging by observers.

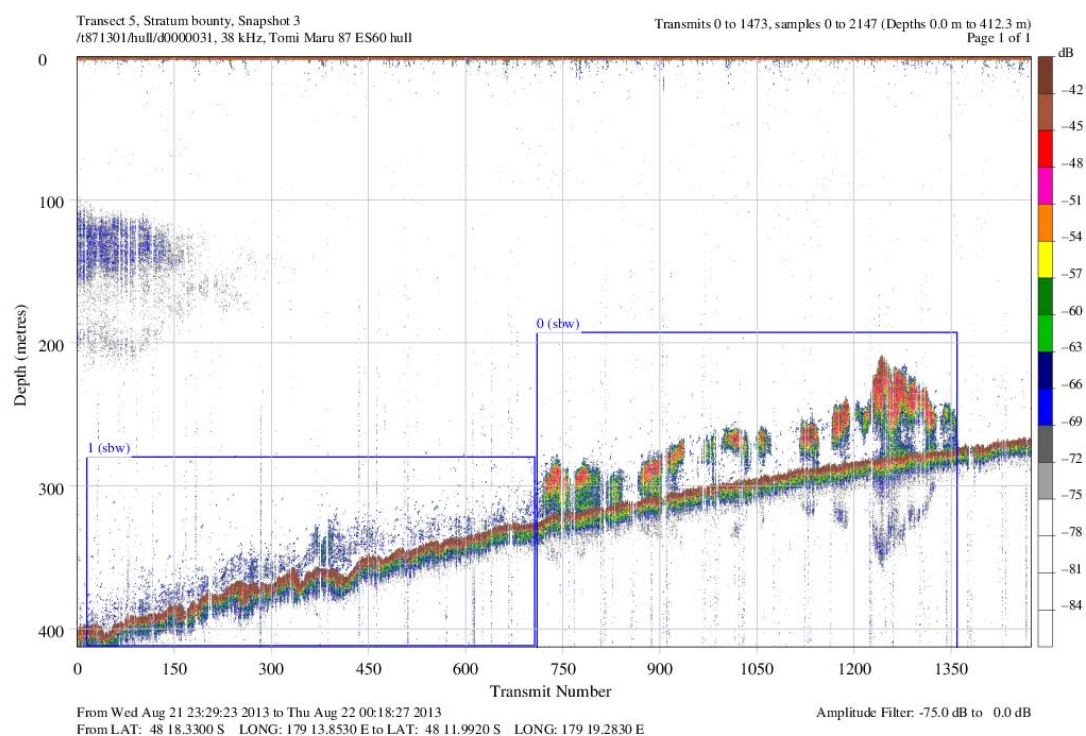


Figure 4: Example of acoustic echogram collected at the Bounty Platform in snapshot 3 on 22 August 2013 showing ping drop-outs due to bubble aeration in poor weather.

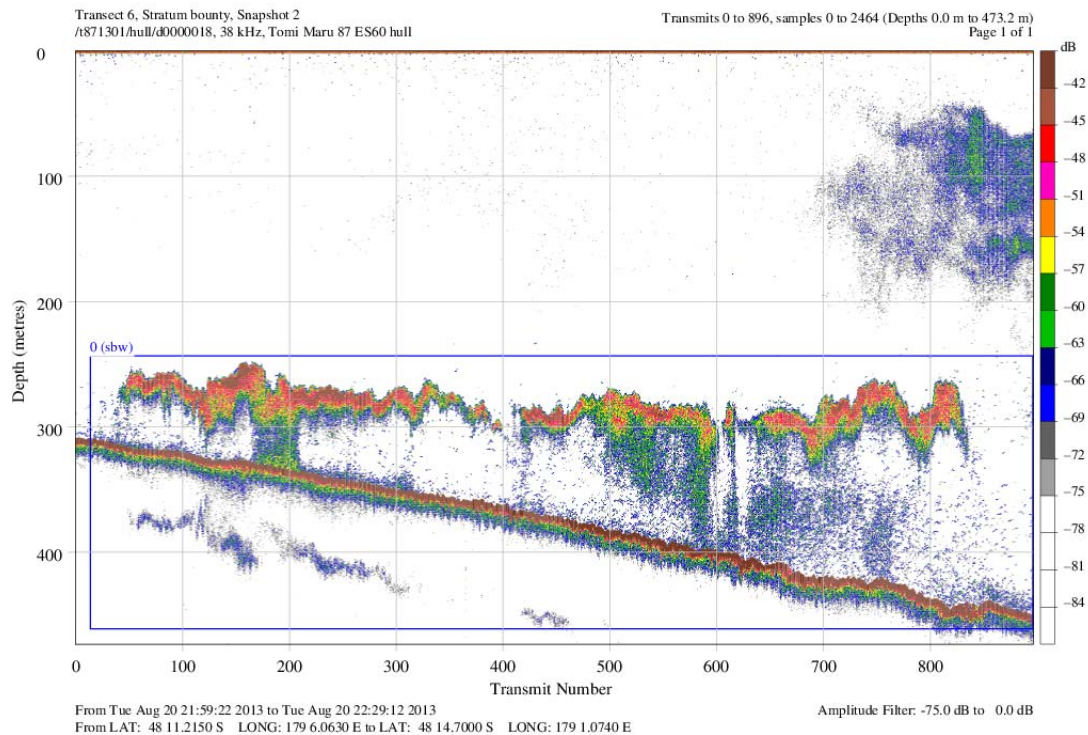


Figure 5: Example of acoustic echogram collected at the Bounty Platform in snapshot 2 on 20 August 2013 showing very strong SBW mark.

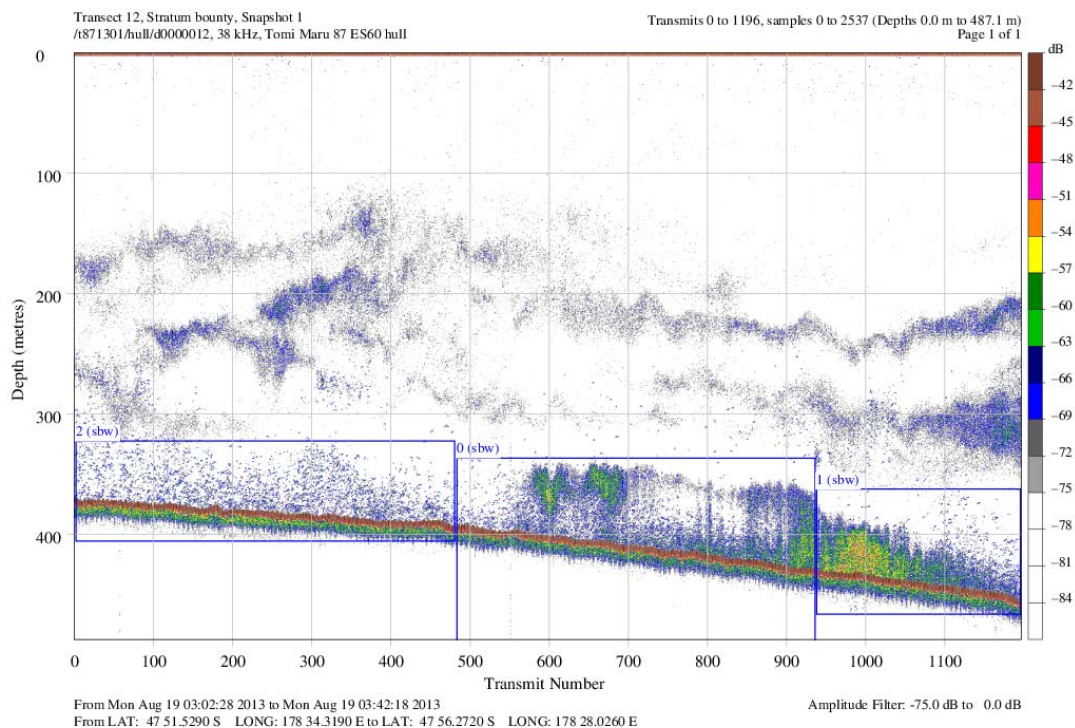


Figure 6: Example of acoustic echogram collected along the westernmost transect in snapshot 1 of the Bounty Platform on 19 August 2013 showing SBW marks. It is likely that marks extended further west.

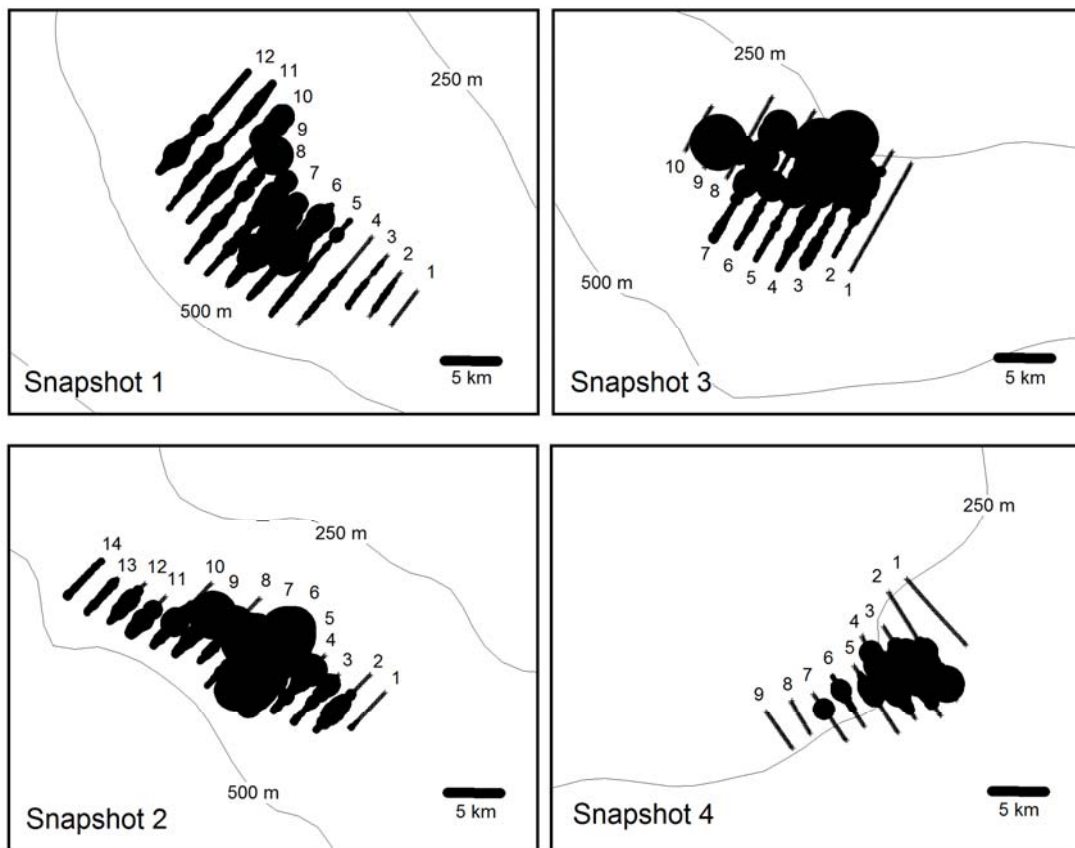
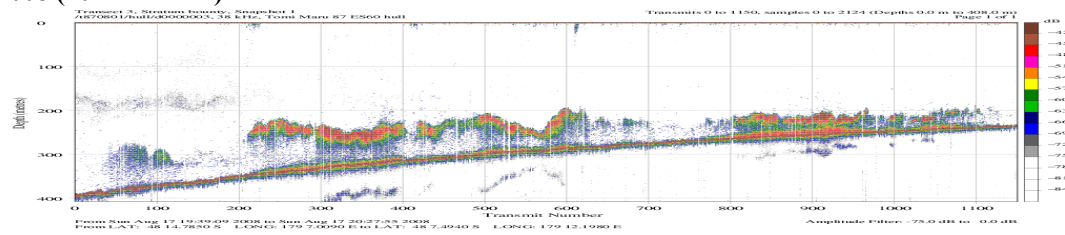
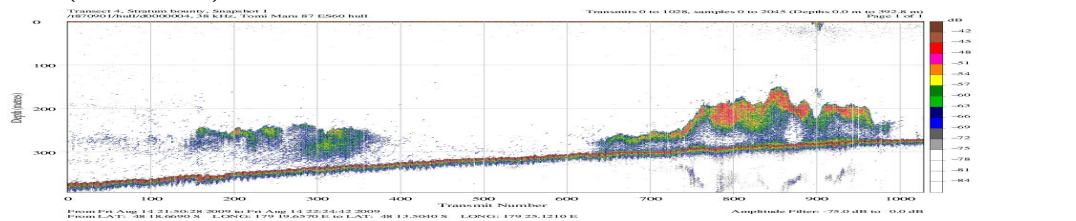


Figure 7: Spatial distribution of SBW backscatter plotted in 10-ping bins for the four snapshots at the Bounty Platform in 2013. Transects are numbered in the order in which they were carried out. Circle area is proportional to the log of the acoustic backscatter. Crosses indicate zero backscatter.

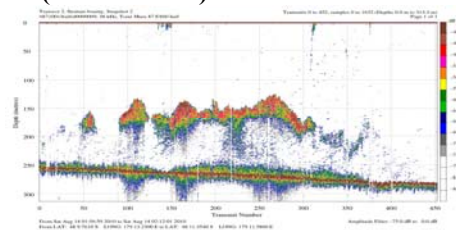
2008 (1027 m² km⁻²)



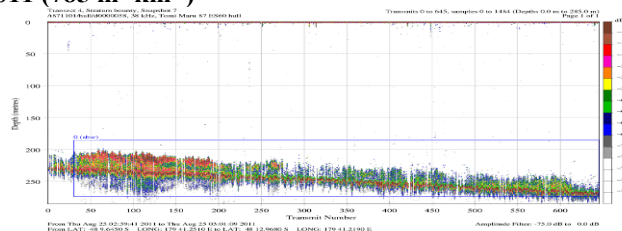
2009 (422 m² km⁻²)



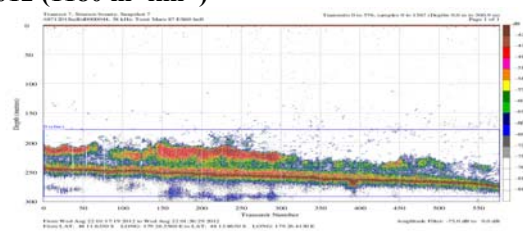
2010 (1029 m² km⁻²)



2011 (785 m² km⁻²)



2012 (1180 m² km⁻²)



2013 (1295 m² km⁻²)

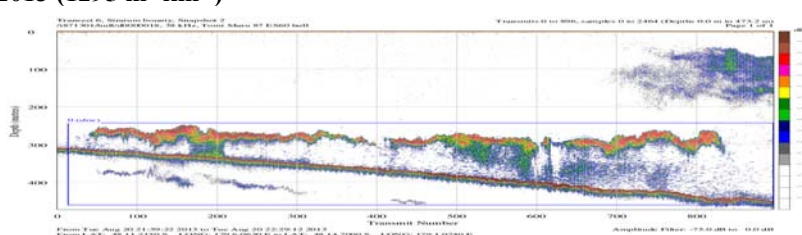


Figure 8: Echograms illustrating the densest SBW marks observed in surveys of the Bounty Platform by FV *Tomi Maru* 87 in 2008–13. Values in parentheses are transect mean density (S_a) values. Echogram size has been scaled so distance scales (x-axes) are equivalent.

APPENDIX 1: Calibration Report: *Tomi Maru* 87 1 July 2013

Calibration of the Simrad ES70 echosounder on FV *Tomi Maru* took place off Timaru (44° 23.9' S 171° 37.2' E) on 1 July 2013. Water depth was about 42 m (below the transducer). This was the ninth time that the echosounder on this vessel has been calibrated, with annual calibrations since 2005. The ES70 computer and software were installed on *Tomi Maru* 87 in April 2010 and connected to the same 38-kHz GPT and transducer as the previous ES60 system. Both the ES60 and ES70 were calibrated together on 30 April 2010 (O'Driscoll & Nelson 2010). Because the ES60 and ES70 use the same hardware, the calibrations with the two software systems were identical within the measurement uncertainty (O'Driscoll & Nelson 2010). The calibration was carried out by Adam Dunford (NIWA) following the procedures in MacLennan & Simmonds (1992).

The ES70 was configured to recommended settings (2000 W power and 1.024 ms pulse). A weighted line was passed under the keel to facilitate setting up the three lines and calibration sphere. Long (3.8 m) fibreglass calibration poles were used to help keep the calibration lines clear of the hull and to allow the rods to point forward. The sphere and associated lines were immersed in a soap solution prior to entering the water. A lead weight was also deployed about 2 m below the sphere to steady the arrangement of lines. The sphere was centered in the beam to obtain data for the on-axis calibration, and was then moved around the beam to obtain data for the beam shape calibration.

The weather was calm with a 7 knot breeze and little swell. The vessel was allowed to drift, and the drift speed was about 0.2 knots. The sphere was located in the beam at 11:40 NZST and the calibration was completed at 12:40 NZST. Calibration data were recorded in two ES60 raw format file (t871301-D20130630-T231800.raw and t871301-D20130701-T001652.raw). Raw data are stored in the NIWA Fisheries *acoustics* database. The ES70 transceiver settings in effect during the calibration are given in Table A1.

Water temperature measurements were taken using an RBR-2050 temperature depth probe (serial number 11817). The water column was essentially unstratified, with a temperature of 10.5° at the surface, increasing slightly to 10.9° at 25 m. The temperature at the depth of the sphere (22 m) was 10.9°. The salinity was not measured and was assumed to be 35 PSU. An estimate of acoustic absorption was calculated using the formulae in Doonan et al. (2003) and an estimate of sound speed was calculated using the formulae of Fofonoff & Millard (1983).

The data in the ES70 files were extracted using custom-written software. The amplitude of the sphere echoes was obtained by filtering on range, and choosing the sample with the highest amplitude. Instances where the sphere echo was disturbed by fish echoes were discarded. The alongship and athwartship beam widths and offsets were calculated by fitting the sphere echo amplitudes to the Simrad theoretical beam pattern:

$$compensation = 6.0206 \left(\left(\frac{2\theta_{fa}}{BW_{fa}} \right)^2 + \left(\frac{2\theta_{ps}}{BW_{ps}} \right)^2 - 0.18 \left(\frac{2\theta_{fa}}{BW_{fa}} \right)^2 \left(\frac{2\theta_{ps}}{BW_{ps}} \right)^2 \right),$$

where θ_{ps} is the port/starboard echo angle, θ_{fa} the fore/aft echo angle, BW_{ps} the port/starboard beamwidth, BW_{fa} the fore/aft beamwidth, and *compensation* the value, in dB, to add to an uncompensated echo to yield the compensated echo value. The fitting was done using an unconstrained nonlinear optimisation (as implemented by the Matlab *fminsearch* function). The Sa correction was calculated from:

$$S_{a,corr} = 5 \log_{10} \left(\frac{\sum P_i}{4P_{max}} \right),$$

where P_i is the sphere echo power measurement and P_{max} the maximum sphere echo power measurement. A value for $S_{a,corr}$ is calculated for all valid sphere echoes and the mean over all sphere echoes is used to determine the final $S_{a,corr}$.

A correction for the triangle wave error in ES70 data (Ryan & Kloser 2004) was also applied as part of the analysis.

Results

The mean range of the sphere and the sound speed and acoustic absorption between the transducer (about 6 m deep) and the sphere are given in Table A2.

The calibration results are given in Table A3. The estimated beam pattern and sphere coverage are given in Figure A1. The symmetrical nature of the pattern and the zero centre of the beam pattern indicate that the transducer and ES70 transceiver were operating correctly. The fits between the theoretical beam pattern and the sphere echoes is shown in Figure A2 and confirms that the transducer beam pattern is correct. The RMS of the difference between the Simrad beam model and the sphere echoes out to 3.5° off axis was 0.19 dB (Table A3), indicating that the calibration was of excellent quality (<0.4 dB is poor, <0.3 dB good, and <0.2 dB excellent).

The estimated peak gain (G_0) based on the mean sphere TS was within 0.04 dB of that estimated in 2012, but 0.12–0.16 dB higher than that from calibrations in 2009–11 (Table A3). The long-term trend for this echosounder is shown in Figure A3 and is consistent with that observed for similar systems overseas (Knudsen 2009). Note that calibration values estimated using fitted or mean sphere TS are more consistent and stable than values based on maximum sphere TS (Figure A3), which was the main reason for re-calculating all previous estimates in the Bounty time-series using G_0 values based on mean sphere TS (see Section 2.5). Previously estimates from 2004–08 used G_0 based on fitted sphere TS, while those from 2009–12 used G_0 based on maximum sphere TS.

Results from the 2013 calibration were used for analysis of results from the 2013 Bounty southern blue whiting survey.

Table A1: ES70 transceiver settings and other relevant parameters during the calibration.

Parameter	Value
Echosounder	ES70
ES70 software version	1.1.0
Transducer model	ES38B
Transducer serial number	1599
ES60 GPT serial number	GPT Q38(4)-F1.0 009072056ac
GPT software version	070413
Sphere type/size	tungsten carbide/38.1 mm diameter
Operating frequency (kHz)	38
Transducer draft setting (m)	0.0
Transmit power (W)	2000
Pulse length (ms)	1.024
Transducer peak gain (dB)	26.5
Sa correction (dB)	0.0
Bandwidth (Hz)	2425
Sample interval (m)	0.3192
Two-way beam angle (dB)	-20.60
Absorption coefficient (dB/km)	9.75
Speed of sound (m/s)	1500
Angle sensitivity (dB) alongship/athwartship	21.90/21.90
3 dB beamwidth (°) alongship/athwartship	7.10/7.10
Angle offset (°) alongship/athwartship	0.0/0.0

Table A2: Auxiliary calibration parameters derived from depth and temperature measurements.

Parameter	Value
Mean sphere range (m)	21.9
S.D. of sphere range (m)	1.4
Mean sound speed (m/s)	1 493
Mean absorption (dB/km)	9.47
Sphere TS (dB re 1m ²)	-42.40

Table A3: Calculated echosounder calibration parameters for *Tomi Maru 87*. All values were calculated using version 7027 of NIWA's Matlab calibration function, with transducer peak gain (G_0) estimated from the mean sphere TS (values in bold). G_0 values calculated using the maximum and fitted TS are given for comparison with earlier reports. Note that 2008 calibration was rejected and was not used in biomass estimation.

Parameter	2013	2012	2011	2010		2009	2008	2007	2006	2005
	ES70	ES70	ES60	ES70	ES60	ES60	ES60	ES60	ES60	ES60
Mean TS within 0.21° of centre	-46.4927	-46.5925	-46.8347	-46.8238	-46.7535	-46.7798	-46.5339	-46.3050	-45.9008	-46.0495
Std dev of TS within 0.21° of centre	0.394	0.4155	0.1645	0.1968	0.4178	0.4025	0.0166	0.2343	0.3639	0.4606
Max TS within 0.21° of centre	-45.6984	-45.9441	-46.4650	-45.9478	-45.9913	-46.0580	-46.5222	-45.8414	-45.4503	-45.2827
No. of echoes within 0.21° of centre	694	340	422	1 274	6 438	279	2	98	17	1 841
On axis TS from beam-fitting	-46.3721	-46.6729	-46.6851	-46.6375	-46.7343	-46.8018	46.3047	-46.2647	-45.9472	-46.0144
G_0 (dB) using mean TS	24.45	24.41	24.29	24.30	24.33	24.31	24.44	24.56	24.74	24.67
G_0 (dB) using fitted TS	24.51	24.36	24.36	24.38	24.33	24.30	24.55	24.57	24.73	24.69
G_0 (dB) using max TS	24.85	24.74	24.48	24.74	24.71	24.67	24.45	24.79	24.96	25.05
Sa correction (dB)	-0.66	-0.66	-0.69	-0.67	-0.71	-0.60	-0.49	-0.65	-0.63	-0.69
Beamwidth (°) alongship/athwarthship	7.0/6.9	7.1/6.8	7.1/6.9	7.0/7.0	6.9/7.0	7.4/7.3	7.1/6.8	7.2/7.3	6.8/7.3	7.0/7.1
Beam offset (°) alongship/athwarthship	-0.00/0.00	-0.00/-0.00	-0.06/-0.05	0.00/0.00	-0.00/0.00	-0.00/-0.00	0.00/0.00	-0.04/-0.12	0.00/0.00	-0.09/0.06
RMS deviation	0.19	0.21	0.11	0.13	0.21	0.20	0.20	0.15	0.20	0.22
Number of echoes	16 544	23 423	29 780	30 727	23 277	7 362	996	1 416	4 632	19 534

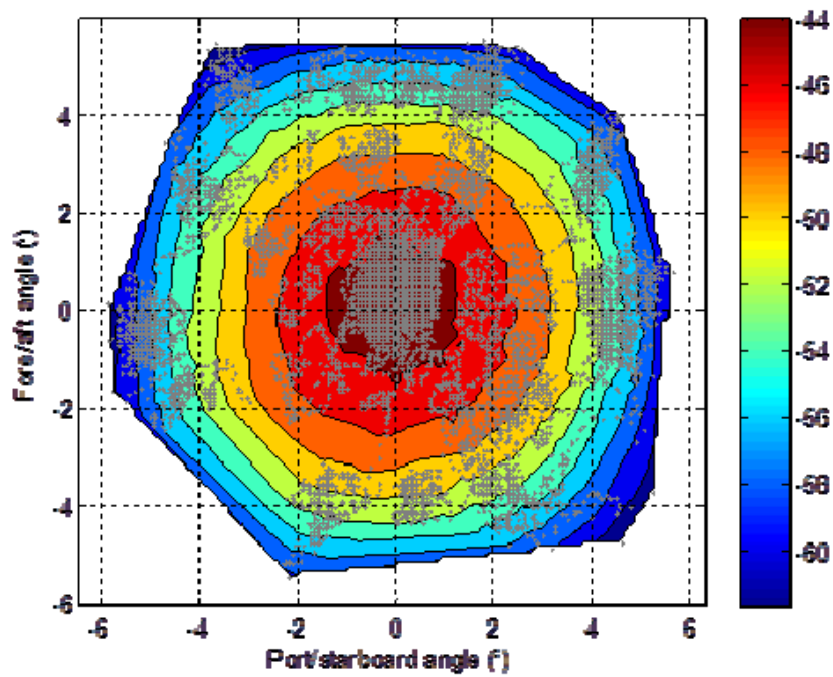


Figure A1: The estimated beam pattern from the sphere echo strength and position for the calibration. The '+' symbols indicate where sphere echoes were received. The colours indicate the received sphere echo strength in dB re 1 m².

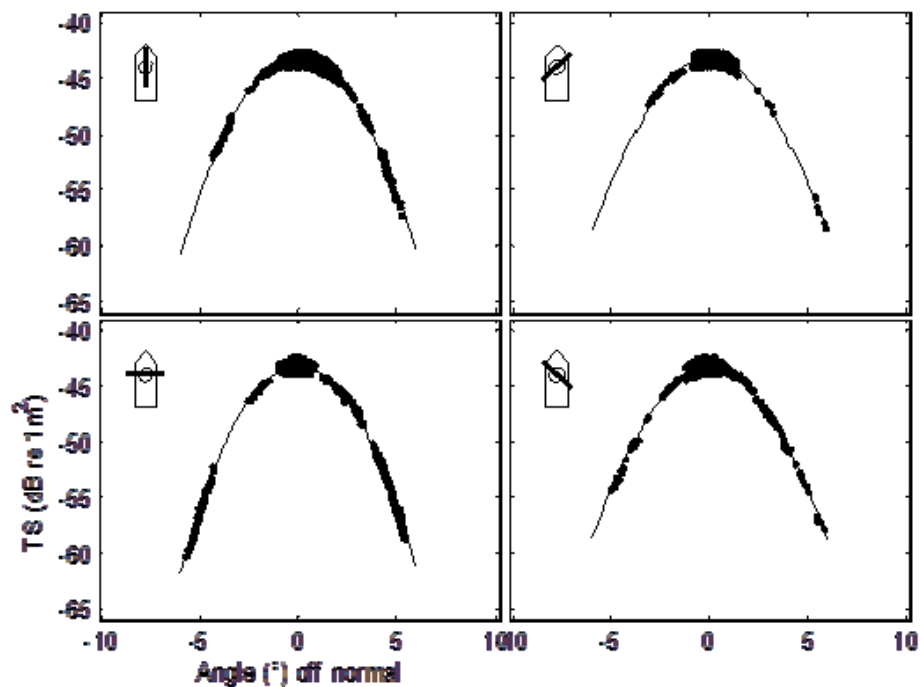


Figure A2: Beam pattern results from the calibration analysis. The solid line is the theoretical beam pattern fit to the sphere echoes for four slices through the beam.

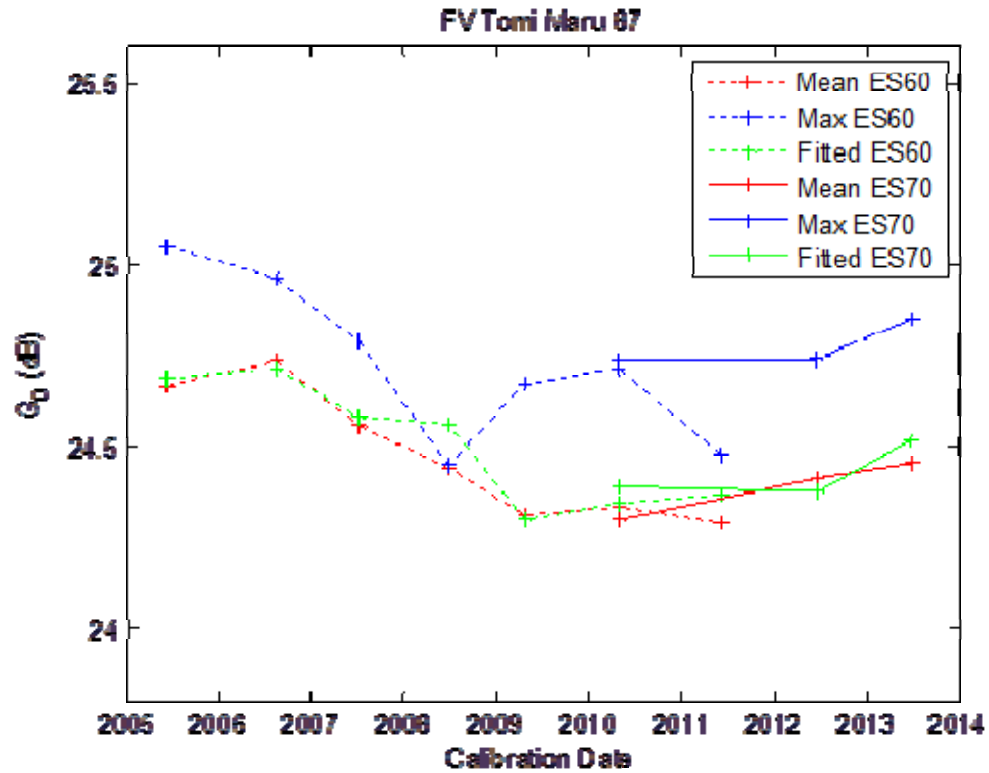


Figure A3: Changes in ‘on axis’ transducer peak gain, G_0 , for the ES60 and ES70 sounders on *Tomi Maru 87*. The various lines refer to the different methods available for estimating the ‘on axis’ target strength of the calibration sphere and hence G_0 .